

**Independent Graduate Modules**, one 21 hours module per week (3 ECTS)

**Deadline for early registration:** - to the modules M01 to M02: ??

- to the modules M03 to M18: ??

M01 PARIS-SACLAY 27/01-31/01	<i>Data-driven Control Design</i>	Claudio De Persis, <i>University of Groningen</i> ; Pietro Tesi, <i>University of Florence</i>
M02 LILLE 10/03-14/03	<i>Modeling and Control of Continuum Soft Robots</i>	Cosimo Della Santina & Daniel Feliu Talegon, <i>TU Delft</i>
M03 PARIS-SACLAY 17/03-21/03	<i>Analysis and Design Methods for Time-Delay Systems</i>	Wim Michiels, <i>KU Leuven</i> ; Silviu-Iulian Niculescu, <i>CNRS, Université Paris-Saclay</i>
M04 ILMENAU 31/03-04/04	<i>Lyapunov Based Design of Sliding Mode Controllers</i>	Jaime Moreno & Leonid Fridman, <i>UNAM, Mexico</i>
M05 LAUSANNE 31/03-04/04	<i>Neural Networks for Optimal Control</i>	Giancarlo Ferrari Trecate, Luca Furieri, Danilo Saccani & Leonardo Massal, <i>EPFL</i>
M06 ZURICH 07/04-11/04	<i>Learning Based Model Predictive Control</i>	Melanie Zellinger, <i>ETH Zurich</i> ; Lorenzo Fagiano, <i>Politecnico di Milano</i> ; Lukas Hewing, <i>The Exploration Company</i>
M07 ROME 07/04-11/04	<i>Static and Dynamic Optimization</i>	Giordano Scarciootti & Thulasi Mylvaganam, <i>Imperial College</i>
M08 LONDON 06/05-09/05	<i>Multi-Agent Optimization and Learning: Resilient and Adaptive Solutions</i>	Nicola Bastianello, <i>KTH</i> ; Ruggero Carli & Luca Schenato, <i>Univ. di Padova</i>
M09 PARIS-SACLAY 12/05-16/05	<i>Dissipativity in Optimal Control - Turnpikes, Predictive Control, and Uncertainty</i>	Lars Grüne, <i>University of Bayreuth</i> ; Timm Faulwasser, <i>TU Hamburg</i>
M10 ISTANBUL 12/05-16/05	<i>Quantify Your Uncertainties: The Input-to-State Stability Framework</i>	Antoine Chaillet, <i>CentraleSupélec</i> ; Iasson Karafyllis, <i>NTU Athens</i>
M11 LIEGE 19/05-23/05	<i>Fast and Flexible Multi-Agent Decision Making</i>	Anastasia Bizyaeva, <i>Cornell University, USA</i> ; Alessio Franci, <i>University of Liège</i>
M12 BARCELONA 19/05-23/05	<i>An Overview on Observer Design Methods for Nonlinear Systems</i>	Vincent Andrieu, & Daniele Astolfi, <i>CNRS, Université de Lyon</i> ; Pauline Bernard, <i>Mines ParisTech</i>
M13 DELFT 02/06-06/06	<i>Formal Methods for Multi-Agent Feedback Control Systems</i>	Lars Lindemann, <i>University of Southern California, USA</i> ; Dimos Dimarogonas, <i>KTH</i>
M14 LOUVAIN-LA-NEUVE 02/06-06/06	<i>Hybrid Control Systems</i>	Ricardo Sanfelice, <i>UC Santa Cruz</i>
M15 ROME 16/06-20/06	<i>Dynamic Control Allocation</i>	Andrea Serrani, <i>Ohio State University, USA</i> ; Sergio Galeani & Mario Sassano, <i>University of Rome, Tor Vergata</i>
M16 OXFORD 16/06-20/06	<i>The Scenario Approach: Data Science for Systems, Control, and Machine learning</i>	Marco G. Campi, <i>University of Brescia, Italy</i> ; Simone Garatti, <i>Politecnico di Milano, Italy</i>
M17 PARIS-SACLAY 23/06-27/06	<i>Introduction to Nonlinear Systems and Control</i>	Hassan K. Khalil, <i>Michigan State University, USA</i>
M18 DUBROVNIK 30/06-04/07	<i>Control and Machine Learning</i>	Martin Lasar, <i>University of Dubrovnik</i> ; Enrique Zuazua, <i>Friedrich-Alexander-Universität Erlangen-Nürnberg</i>
M19 MILAN 30/06-04/07	<i>Deep Learning for System Identification</i>	Dario Piga & Marco Forgione, <i>SUPSI, Lugano</i>

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