The Rayleigh–Taylor Condition for the Muskat Problem

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D. H. Sharp, *An Overview of Rayleigh–Taylor Instability*, Physica D, 1984:

Thus we can infer a simple criterion for the onset of Taylor instability at the interface between two fluids of different densities: If the heavy fluid pushes the light fluid, the interface is stable. If the light fluid pushes the heavy fluid, the interface is unstable. A







Factor	Relative size of effect (dimensionless parameter)	Effect on growth of instability
Density ratio	$\rho_{\rm H}/\rho_{\rm L}$ or $A = (\rho_{\rm H} - \rho_{\rm L})/(\rho_{\rm H} + \rho_{\rm L})$	A key factor governing the growth rate of Rayleigh-Taylor or Kelvin-Helmholtz instability for small amplitude perturbations of wavelength λ .
Surface tension	Weber number = $2\sigma/(\rho_{\rm H}-\rho_{\rm L})g^{1/2}$	In linear theory, stabilizes wavelengths shorter than a critical wavelength $\lambda = \sqrt{\sigma/g} (\rho_{\rm H} - \rho_{\rm L})$. Establishes a most unstable wavelength, hence probably makes problem well posed mathematically.
Viscosity	$R = vt/\lambda^2$	Reduces growth rate; regularizes fluid flow.
Compressibility	$G = g/kc^2 = \frac{(\text{phase velocity of gravity waves})^2}{(\text{sound speed})^2}$	Reduces growth rate of long wavelength perturbations; decreases active volume of fluid.
Heterogeneity	$\Delta L/\lambda, \Delta v/v \dots$	Can excite secondary, tertiary, instabilities of various wavelengths.

Table I Some factors influencing the development of Rayleigh-Taylor instability



The governing equations

Consider the following two-phase flow





The flow in the bulk is governed by Darcy's law:

$$\mu_{\pm}\vec{v}_{\pm} = -K \cdot \nabla u_{\pm}, \qquad K \in \mathbb{R}^{n \times n}_{\text{sym}}, \ K > 0.$$

 \rightarrow common model for laminar flows in porous media and flows in Hele-Shaw cells.

Kinematic boundary condition on the upper free interface:

 $\mu_+\partial_t h + \partial_\nu u_+ = 0$ on $\Gamma(h)$,

 \rightarrow particles on $\Gamma(h)$ stay there. Additional *dynamic* boundary condition:

 $u_+ = g \rho_+ h$ on $\Gamma(h)$,

 \rightarrow balance of forces on Γ (zero air pressure, no surface tension effects).

On the interface between the fluids:

$$\mu_{-}\partial_{t}f + \partial_{\nu}u_{-} = 0 \quad \text{on} \quad \Gamma(f),$$

 \rightarrow again kinematic boundary condition and continuity of pressure:

$$u_{+} - u_{-} = g(\rho_{+} - \rho_{-})f$$
 on $\Gamma(f)$.



Summarising ($K = k \cdot id$), we get the following *Muskat* problem:

Δu_+	=	0	in $\Omega(f,h)$
Δu_{-}	=	0	in $\Omega(f)$
$\mu_+\partial_t h + k\partial_ u_+$	=	0	on Γ(<i>h</i>)
<i>u</i> +	=	${old g} ho_+{old h}$	on Γ(<i>h</i>)
$u_{+} - u_{-}$	=	$g(\rho_+ - \rho)f$	on $\Gamma(f)$
$\mu\partial_t f + k\partial_ u$	=	0	on Γ(<i>f</i>)
$\partial_y u$	=	Ь	on Γ_{-1}

where b(x) is a given injection rate on Γ_{-1} .





Application in pertoleum engineering¹:



 1 M Muskat: Two fluid systems in porous media. The encroachment of water into an oil sand, J. Appl. Physics, 5 (1934), 250 – 264



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Proposition 1 (A. Matioc, B. Matioc & JE, Nonlinearity, 2012)

 The Muskat problem is locally well-posed in the classical sense, provided that

$$b\mu_+ + g
ho_+\mu_- > 0$$

 $rac{\mu_+ - \mu_-}{\mu_+ + \mu_-} (b - g
ho_+) + g(
ho_+ -
ho_-) < 0$

(generalised Rayleigh–Taylor conditions).

- If $\rho_- > \rho_+$ then the flat solution is asymptotically stable.
- If ρ₊ > ρ₋, b = g ρ₊, and surface tension is included (and used as a bifurcation parameter) on Γ(f) then there are finger shaped unstable steady states of the form:



Finger shaped steady states for the Muskat problem:





Related papers (not complete):

- Friedman and Y. Tao., Nonlinear Analysis TMA, 2003
- Siegel, Caflish, Howison, CPAM, 2004
- Cordoba, Cordoba, Gancedo, Annals Math., 2011
- Prüss, Simmonett, Evol. Equ. Control Theory, 2016
- B. Matioc, Ch. Walker, JE, Indiana Univ. Math. J., 2018



Assume

- *b* ≡ 0
- oil as fluid + with: $ho_+=$ 900 kg/m³, $\mu_+=$ 100 mPas
- water as fluid with: $ho_-=1000\,kg/m^3$, $\ \ \mu_-=1\,mPas$
- \rightarrow Muskat problem is well-posed.
- In application to oil production:
 - *b* > 0
 - oil as fluid + with: $ho_+=$ 900 kg/m³, $\mu_+=$ 100 mPas
 - water as fluid with: $ho_-=1000\,kg/m^3$, $\mu_-=1\,mPas$

 \rightarrow Then the Muskat problem is no longer well-posed, in cases where b becomes too large.

- Friedman and Y. Tao., 2003: equal densities, $b=0. \rightarrow$ well-posed if $\mu_+ > \mu_-.$
- Siegel, Caflish, Howison, 2004: equal densities, $b=0. \rightarrow$ well-posed if $\mu_+>\mu_-.$
- Cordoba et al. 2011: equal viscosities, $\rho_- > \rho_+$.



$$(RT) \qquad egin{array}{ccc} b\mu_+ + g
ho_+\mu_- &> 0\ rac{\mu_+-\mu_-}{\mu_++\mu_-}(b-g
ho_+) + g(
ho_+-
ho_-) &< 0 \end{array}$$

are the Rayleigh-Taylor (RT) condition for the flat equlibrium.

With the associated pressures

$$p_{\pm} = u_{\pm} - g \rho_{\pm} y$$

(RT) are equivalent to

 $\partial_{\nu} p_+ < 0$ on [y = 2] $\partial_{\nu} p_- - \partial_{\nu} p_+ < 0$ on [y = 1]



Proposition 2 (B. Matioc, Ch. Walker & JE, Indiana Univ. Math. J., 2018)

• Given (f_0, h_0) of class $C^{2+\alpha}$, the Muskat problem is locally well-posed in the classical sense, provided that

 $\partial_{\nu} p_{+} < 0 \quad \text{on} \quad \Gamma(h_{0})$ $\partial_{\nu} p_{-} - \partial_{\nu} p_{+} < 0 \quad \text{on} \quad \Gamma(f_{0})$

• The Muskat problem is backward parabolic when the Rayleigh-Taylor conditions hold with reversed inequalities.



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- The Rayleigh–Taylor conditions ensure that this system is parabolic in the sense that its propagator is a sectorial operator.
- Maximal regularity then yields the well-posedness result.
- The finger shaped steady states are obtained as bifurcation branches, where the surface tension coefficient serves as a bifurcation parameter.



The symbols of the linearisation:

$$\begin{split} \lambda_{1}^{f}(m) &= \left[A_{\mu}(b - g\rho_{+}) + g(\rho_{+} - \rho_{-}) - \gamma_{f} m^{2} \right] \frac{k|m|}{\Sigma_{\mu} \tanh(|m|)}, \\ \lambda_{2}^{f}(m) &= \left[\frac{b[\mu]_{\pm} + 2g\rho_{+}\mu_{-}}{\Sigma_{\mu}} - g\rho_{-} - \gamma_{f} m^{2} \right] \frac{k|m|}{\Sigma_{\mu} \sinh(|m|)}, \\ \lambda_{1}^{h}(m) &= - \left[\frac{g\rho_{+}\mu_{-} + b\mu_{+}}{\Sigma_{\mu}} + \gamma_{h} m^{2} \right] \frac{k|m|}{\Sigma_{\mu} \sinh(|m|)}, \\ \lambda_{2}^{h}(m) &= - \left[\frac{b\mu_{+} + g\rho_{+}\mu_{-}}{\Sigma_{\mu}} + \gamma_{h} m^{2} \right] \frac{k|m|}{\mu_{+} \tanh(|m|)} - \frac{\mu_{-}}{\mu_{+}} \frac{\lambda_{1}^{h}(m)}{\cosh(m)}. \end{split}$$

Here, A_{μ} is the Atwood number

$$A_{\mu} := (\mu_{+} - \mu_{-})/(\mu_{+} + \mu_{-})$$

and $\Sigma_{\mu} := \mu_{+} + \mu_{-}$.

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Thin film approximation

Using the scaling

$$x = \tilde{x}, \quad y = \varepsilon \tilde{y}, \quad t = \varepsilon \tilde{t} \quad f = \varepsilon \tilde{f}, \quad h = \varepsilon \tilde{h},$$

and expanding

$$ilde{u}_+ = \sum_{k=0}^\infty v_+^k arepsilon^k, \qquad ilde{u}_- = \sum_{k=0}^\infty v_-^k arepsilon^k$$

the limit $\varepsilon \searrow 0$ yields:



A system of degenerated parabolic equations for the film heights f and h:

$$\begin{aligned} \partial_t f &= \partial_x (f \partial_x f) + R \partial_x (f \partial_x h), \\ \partial_t h &= \partial_x (f \partial_x f) + R_\mu \partial_x \left[(h - f) \partial_x h \right] + R \partial_x (f \partial_x h) \end{aligned}$$
(1)

for $(t, x) \in (0, \infty) \times (0, L)$ and subject to homogeneous Neumann boundary conditions. Moreover:

$$R := rac{
ho_+}{
ho_- -
ho_+}, \qquad R_\mu := rac{\mu_-}{\mu_+} R.$$



Proposition 3 (A. Matioc, B. Matioc & JE)

The system (1) is classically well-posed for positive initial conditions and the flat steady state is asymptotically stable in H^2 , provided that $\rho_- > \rho_+$.

Observe that in Proposition 3 the full Rayleigh–Taylor conditions have been replaced by $\rho_- > \rho_+$.

Fundamental idea of this approach: Realise the system on a phase space of positive functions as a regular quasilinear parabolic system.



In what follows:

- Construction of global weak solutions to (1) emerging from *nonnegative* initial conditions,
- evidence of global *L*₂-stability of weak solutions.

For g := h - f the system becomes more symmetric:

$$\partial_t f = (1+R)\partial_x(f\partial_x f) + R\partial_x(f\partial_x g),$$

$$\partial_t g = R_\mu \partial_x(g\partial_x f) + R_\mu \partial_x(g\partial_x g).$$

(2)



Furthermore, there are two energy functionals:

$$\mathcal{E}_1(f,g) := \int_0^L \left[(f \ln f - f + 1) + \frac{\mu_-}{\mu_+} (g \ln g - g + 1) \right] dx$$

of entropy-type and

$$\mathcal{E}_2(f,g) := \int_0^L \left[f^2 + R(f+g)^2 \right] dx$$

of L_2 -type.



Proposition 4 (Ph. Laurençot, B. Matioc & JE)

Assume that R > 0 and $R_{\mu} > 0$. Given $f_0, g_0 \in L_2((0, L))$ with $f_0 \ge 0$ and $g_0 \ge 0$, there exist a global weak solution (f, g) of (2) satisfying

- $f \ge 0, g \ge 0$ in $(0, T) \times (0, \infty)$,
- $f, g \in L_{\infty}((0, T), L_{2}((0, L))) \cap L_{2}((0, T), H^{1}((0, L))),$
- $||f(T)||_1 = ||f_0||_1$, $||g(T)||_1 = ||g_0||_1$,
- $\mathcal{E}_j(f(T), g(T)) \leq \mathcal{E}_j(f_0, g_0)$ for j = 1, 2

for all T > 0.

In addition, the rate of dissipation of both energies can be estimated from above.



In particular we have:

$$\mathcal{E}_1(f(T), g(T)) + c_R \int_0^T \int_0^L \left(|\partial_x f|^2 + |\partial_x g|^2 \right) \, dx \, dt \le \mathcal{E}_1(f_0, g_0)$$

for all $T \ge 0$.

This estimates is obviously most helpful in deriving H^1 -estimates of solutions.



Proposition 5 (Global exponential stability)

Under the assumptions of Proposition 3 there exist positive constants M and ω such that

$$\left\| f(t) - \frac{1}{L} \int_0^L f_0 dx \right\|_2^2 + \left\| g(t) - \frac{1}{L} \int_0^L g_0 dx \right\|_2^2 \le M e^{-\omega t}$$
for a.e. $t \ge 0$.

To get a regularised system, let

$$egin{aligned} \mathcal{F}_arepsilon &:= (1-arepsilon^2\partial_{x}^2)^{-1}f, \qquad \mathcal{G}_arepsilon &:= (1-arepsilon^2\partial_{x}^2)^{-1}g. \end{aligned}$$

for $\varepsilon > 0$ and $f, g \in L_2((0, L))$. Then we consider:

The regularised system

$$\partial_t f_{\varepsilon} = (1+R)\partial_x (f_{\varepsilon}\partial_x f_{\varepsilon}) + R\partial_x (f_{\varepsilon}\partial_x G_{\varepsilon}), \partial_t g_{\varepsilon} = R_{\mu}\partial_x (g_{\varepsilon}\partial_x F_{\varepsilon}) + R_{\mu}\partial_x (g_{\varepsilon}\partial_x g_{\varepsilon}),$$

$$(3)$$

with regularised initial data

$$f_{0\varepsilon} := (1 - \varepsilon^2 \partial_x^2)^{-1} f_0 + \varepsilon, \quad g_{0\varepsilon} := (1 - \varepsilon^2 \partial_x^2)^{-1} g_0 + \varepsilon.$$

The off-diagonal terms of (3) then are of lower order.

- \rightarrow system (3) is parabolic (at least on positve solutions)
- \rightarrow existence of local classical solutions and a criterion for global solutions:



Let $T_+(\varepsilon)$ denote the positive exit time of the solution. If for every $T < T_+(\varepsilon)$ there exists a $C(\varepsilon, T) > 0$ such that

$$f_{arepsilon} \geq arepsilon/2 + C(arepsilon, T)^{-1}, \quad g_{arepsilon} \geq arepsilon/2 + C(arepsilon, T)^{-1}.$$

and

$$\max_{t\in[0,T]} \|(f_{\varepsilon}(t),g_{\varepsilon}(t))\|_{H^1} \leq C(\varepsilon,T),$$

then the solution $(f_{\varepsilon}(t), g_{\varepsilon}(t))$ exists globally.



Furthermore:

The energy estimate for \mathcal{E}_1 carries over to the regularised system!

ightarrow uniform H^1 -estimates for $(f_{arepsilon}, g_{arepsilon})$

ightarrow global existence of $(f_{arepsilon}, g_{arepsilon})$

Using again the energy estimate for $\mathcal{E}_1,$ we get uniform estimates of the form

$$\int_0^T \left(\|h_\varepsilon(t)\|_{H^1}^2 + \|h_\varepsilon(t)\|_{L_3}^3 + \|\partial_t h_\varepsilon(t)\|_{(W_6^1)'}^{6/5} \right) dt \leq C(T)$$

for $h \in \{f, g, F, G\}$ and all $(\varepsilon, T) \in (0, 1) \times (0, \infty)$.

These estimates form the core of the construction of weak solutions.

Thank you!

